

# Concurrent Collections are Deterministic

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# *This talk*

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- ◆ **Determinism = deterministic input-output behavior**
- ◆ **Want: determinism by design; nondeterminism is a bug**
- ◆ **Theme: abstraction → determinism**
- ◆ **Goal 1: run-time check of determinism plus proof**
  - **Concurrent collections are deterministic: why and how**
- ◆ **Goal 2: compile-time check plus low annotation burden**
  - **Plasma simulation in X10: is load balancing deterministic?**

# Analogy

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- ◆ **Determinism in the 2010s = type checking in the 1980s**
- ◆ **The code was designed to satisfy the property**
- ◆ **The developers think the code satisfies the property**
- ◆ **Testing suggests the code satisfies the property**
- ◆ **The expert developers don't want a new type system**
- ◆ **Average programmers need help!**

# ***Concurrent collections are deterministic***

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- ◆ **Idea 1: dynamic single assignment**
  - Or: forbid races
- ◆ **Idea 2: blocking read**
  - Or: forbid uninitialized-variable errors

# Featherweight CnC syntax

- ◆ Program:  $p ::= f_i (\text{int } a) \{ d_i s_i \}, i \in 1..n$
- ◆ Declaration:  $d ::= n = \text{data.get}(e); d$   
|  $\varepsilon$
- ◆ Statement:  $s ::= \text{skip}$   
|  $\text{if } (e > 0) s1 \text{ else } s2$   
|  $\text{data.put}(e1, e2); s$   
|  $\text{prescribe } f_i(e); s$
- ◆ Expression:  $e ::= \dots$

## Featherweight CnC semantics (1/3)

A state in the semantics:  $(A, T)$  or error

$$T ::= T \parallel T \quad | \quad d \ s$$
$$(A, \text{if } (e > 0) \ s1 \ \text{else } s2) \rightarrow (A, s1) \quad (\text{if } \text{eval}(e) > 0)$$
$$(A, \text{if } (e > 0) \ s1 \ \text{else } s2) \rightarrow (A, s2) \quad (\text{if } \text{eval}(e) \leq 0)$$
$$(A, \text{prescribe } f_i(e); \ s) \rightarrow (A, (d_i, s_i)[a := \text{eval}(e)] \parallel s)$$

## Featherweight CnC semantics (2/3)

$$(A, \text{skip} \parallel T2) \rightarrow (A, T2)$$
$$(A, T1 \parallel \text{skip}) \rightarrow (A, T1)$$
$$(A, T1) \rightarrow \text{error}$$
$$(A, T2) \rightarrow \text{error}$$

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$$(A, T1 \parallel T2) \rightarrow \text{error}$$

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$$(A, T1 \parallel T2) \rightarrow \text{error}$$
$$(A, T1) \rightarrow (A', T1')$$
$$(A, T2) \rightarrow (A', T2')$$

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$$(A, T1 \parallel T2) \rightarrow (A, T1' \parallel T2)$$

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$$(A, T1 \parallel T2) \rightarrow (A, T1 \parallel T2')$$

## *Traditional semantics*

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$(A, \text{item.put}(e1, e2); s) \rightarrow (A[\text{eval}(e1) := \text{eval}(e2)]; s)$

$(A, n = \text{data.get}(e); d s) \rightarrow (A, (d s)[n := A(\text{eval}(e))])$

if  $A(\text{eval}(e))$  is defined

$(A, n = \text{data.get}(e); d s) \rightarrow \text{error}$ , if  $A(\text{eval}(e))$  is undefined

## CnC semantics (3/3)

$(A, \text{item.put}(e_1, e_2); s) \rightarrow (A[\text{eval}(e_1) := \text{eval}(e_2)]; s)$

(dynamic single assignment) if  $A(\text{eval}(e_1))$  is undefined

$(A, \text{item.put}(e_1, e_2); s) \rightarrow \text{error}$ , if  $A(\text{eval}(e_1))$  is defined

$(A, n = \text{data.get}(e); d s) \rightarrow (A, (d s)[n := A(\text{eval}(e))])$

(blocking read) if  $A(\text{eval}(e))$  is defined

~~$(A, n = \text{data.get}(e); d s) \rightarrow \text{error}$ , if  $A(\text{eval}(e))$  is undefined~~

# Concurrent collections are deterministic

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We use  $\sigma$  to range over states.

A **final state** is one of:

- ◆ (A, skip)
- ◆ error
- ◆ (A, T) that hangs: all reads are blocked

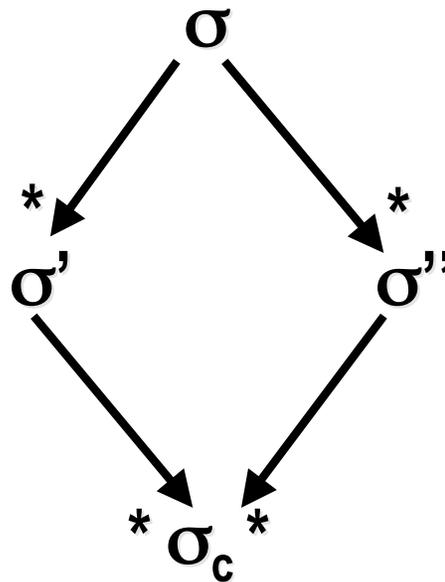
Theorem: If  $\sigma \rightarrow^* \sigma'$  and  $\sigma \rightarrow^* \sigma''$  and  $\sigma', \sigma''$  are **final states**,  
then  $\sigma' = \sigma''$ .

## *Proof of determinism*

Lemma: (Confluence, Church-Rosser [1936])

If  $\sigma \rightarrow^* \sigma'$  and  $\sigma \rightarrow^* \sigma''$ ,

then there exists  $\sigma_c$  such that  $\sigma' \rightarrow^* \sigma_c$  and  $\sigma'' \rightarrow^* \sigma_c$



## Switching gears to X10 now

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- ◆ **X10 = imperative language**
  - + **async // *parallelism***
  - + **finish // *synchronization***
- ◆ **Want: determinism without annotations**
- ◆ **Determinism = may-happen-in-parallel analysis**
  - + **effect analysis**

## ***Plasma simulation in Fortran → X10***

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- ◆ Originally programmed in Fortran + MPI + pthreads by Viktor Decyk at UCLA
- ◆ Particle-in-cell computation
- ◆ Has run on many parallel hardware platforms over 20 years
  - 12 billion particles on 4,096 processors for months
- ◆ 3D version: 100,000 lines of Fortran
- ◆ 2D version: 10,000 lines of Fortran
  - 4,623 lines of X10



## May-happen-in-parallel analysis [PPOPP 2010]

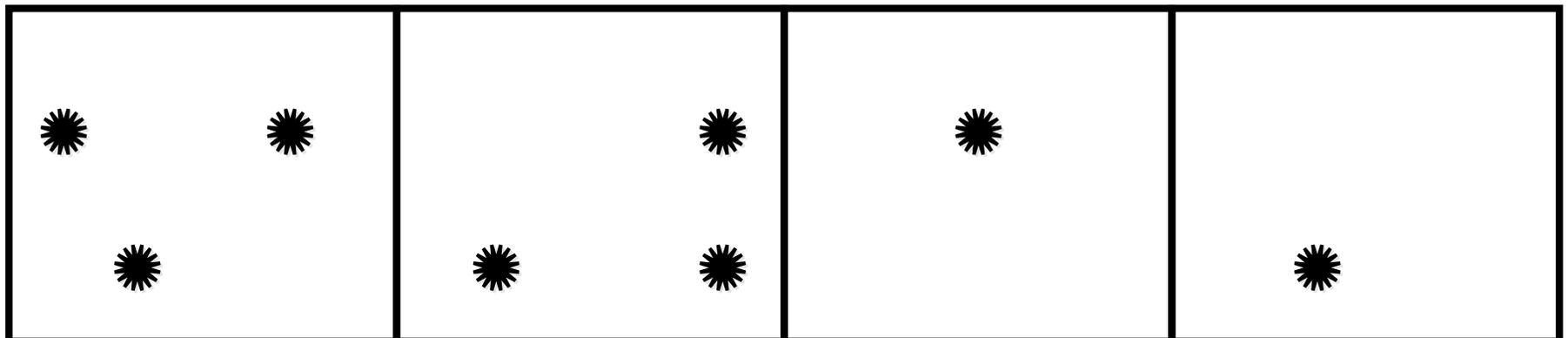
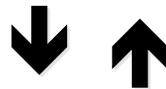
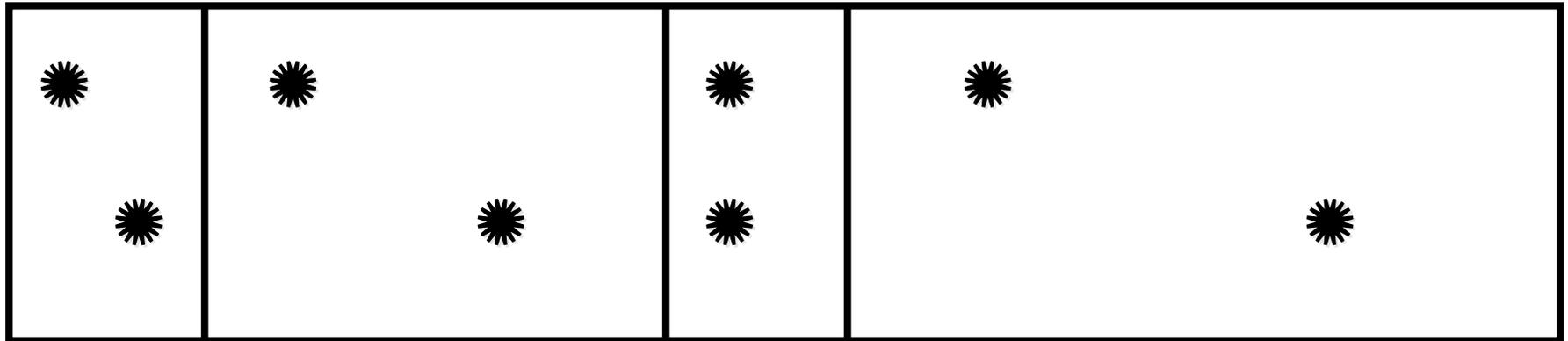
- ◆ For a program  $p$ ,  
let  $MHP(p)$  be the true may-happen-in-parallel information
- ◆ **Theorem:** if  $\vdash p : E$ , and  $E(\text{main}) = (M, O)$   
then  $MHP(p) \subseteq M$
- ◆ Type inference: given  $p$ , find  $E$  such that  $\vdash p : E$
- ◆ Type inference by constraint solving

## *MHP analysis of the plasma benchmark*

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- ◆ plasma benchmark: 4,623 LOC; 151 async; 84 finish; 505 call
- ◆ 11,422 constraints
- ◆ About 16 seconds to solve the constraints (257 MB space)
- ◆ #pairs of async bodies that may happen in parallel:
  - Self: 134 (in parallel with itself)
  - Same: 120 (two different async bodies in the same method)
  - Diff: 4 (two async bodies in different methods)
  - Total: 258
- ◆ We didn't find any false positives!

# *Plasma simulation does load balancing*



# Plasma simulation benchmark

```
class Particle { ... } ...
```

```
dist(:rank == 1) d = ...;
```

```
Particle[:rank == 1] a = new Particle[d](...);
```

```
while (...) { // 200,000 iterations
```

```
    ... a[i] = ... a[j] ...           // 2/3 computation
```

```
    d = ...;
```

```
    a = new Particle[d](...a[i]...a[j]...); // 1/3 communication
```

```
}
```

# ***Conclusion***

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- ◆ **Average programmers need determinism**
- ◆ **Determinism for CnC !**
- ◆ **Determinism for X10 ? Annotations?**
- ◆ **Challenge: load balancing for arrays of references**